An introduction to the newest edition of

AISC's $z_{i^{\dagger}}$ $z_{i^{\dagger}}$ $z_{i^{\prime}}$



DO YOU DESIGN PROJECTS with seismic systems? If so, good news: AISC has just released the 3rd Edition $\gamma_{t} = \gamma_{t} = \gamma_{t} = \gamma_{t}$

This edition has been expanded with new discussion and design examples to help engineers navigate the design of steel and composite Seismic Force Resisting Systems (SFRS). It includes discussion and practical guidance on applying the latest versions of AISC's core standards—the 2016 (ANSI/ AISC 360), 2016

The new edition contains more than 60 examples that demonstrate how to design the key members and connections for the most commonly used SFRS. The examples go beyond just seismic-speci c checks to also demonstrate the full design, limit state by limit state. The manual is a valuable resource not only for those who design in the seismic world, but for anyone interested in learning the procedures used for designing members, connections and systems.

The overall organization of the $\frac{1}{2}$, $\frac{1}{2}$, $\frac{1}{2}$, $\frac{1}{2}$ has not changed from the 2nd Edition, and the chapters are still organized as follows:

Part 1: General Design Considerations

Part 2: Analysis

Part 3: Systems Not Speci cally Designed for Seismic Resistance

Part 4: Moment Frames

Part 5: Braced Frames

Part 6: Composite Moment Frames

Part 7: Composite Braced Frames and Shear Walls

Part 8: Diaphragms, Collectors and Chords

Part 9: Provisions and Standards

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Let's take a brief look at these various parts. The manual starts off strong in the Scope section, which outlines cases where the $\gamma_{t} = \rho \bullet \rho_{t} + \rho \bullet \rho_{t}$ need to be followed

Following the Scope is Part 1, General Design Considerations, an overview of seismic design concepts. Discussion is provide on topics such as the performance goals for seismic design, anticipated behavior of different systems, drift, quality control, quality assurance, design drawing requirements and referenced standards. The section comparing the notable differences between wind and seismic design offers guidance on how to properly account for the governing loading conditions, particularly in regions or building types where there is no obvious controlling design methodology.

Part 1 also covers the symbols and terminology found in ASCE/SEI 7 that are pertinent to steel seismic design. Seismic performance factors such as the seismic modication coef cient, \rightarrow , de ection ampli cation factor, \downarrow , overstrength factor, Ω_0 , and redundancy factor, ρ , are introduced and discussed in detail.





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When it comes to conveying the various seismic elements in the design documents, Part 1 now includes a section that will be bene cial to the engineers generating these documents and to any other members of the construction team that use them. Instruction is given for properly indicating SFRS members on plans and elevations, identifying protected zones and calling out demand-critical welds, among other items. To give an idea of what this entails, a sample plan has been generated with SFRS elements such as brace frames, moment frames, collectors and chords identi ed for both orthogonal directions. A fully developed connection detail and schedule illustrating one method for communicating connection design information, following the requirements of the γ_{1} θ φ_{1} η η is also provided (Figure 1).

A number of useful design aid tables are also found in Part 1. Table 1-1 gives dimensions for detailing weld access holes using the alternate geometry for seismic applications as found in AWS D1.8. Table 1-2 is a reference for quickly determining member ductility requirements for each of the SRFS covered in the the steel member sizes that satisfy widthto-thickness requirements for W-Shapes, angles, rectangular and square HSS and round HSS. The W-shape tables have been expanded to include ASTM A913 Grades 65 and 70 in addition to ASTM A992. The HSS tables are updated from ASTM A500 Grade B to A500 Grade C, corresponding to what is now the preferred material speci cation, as shown in AISC ____ Table 2-4. The HSS tables now also include ASTM A1085 as this material becomes more readily available in the industry. These new high-strength materials are consistent with updates in and are used in several of the design examples. For convenience, the steel and composite system portions of ASCE/

\ , Part 2, Analysis, provides an overview of the analysis procedures in ASCE/SEI 7, the AISC $\mathbf{a}_{11}^{(1)} \mathbf{a}_{11}^{(1)} \mathbf{a}_{11}^{(1)$ r_{ij} . Three methods for stability design included in the r_{ij} , are the direct analysis method, effective length method and rst-order method. ASCE/SEI 7 then covers three analysis methods, including the equivalent lateral force method, modal response spectrum analysis and nonlinear response history analysis. In Part 2, guidance is provided on implementing the equivalent lateral force method or modal response spectrum analysis using the direct analysis method.

Modeling techniques are recommended regarding steel and composite member stiffness, connection panel zones with rigid offsets, diaphragms, column bases and foundations. The discussion of ductile design mechanism and capacity-based design addresses fundamental topics in seismic design.

G Part 3, Systems not Speci cally Designed for Seismic Resistance, is a standalone chapter that covers designs that do not need to follow the requirements of the $\gamma_{i^{t}-i^{t}} \bullet \bullet \gamma_{i^{t}} \bullet \cdots$. Oftentimes, there is a misconception that, when designing an \rightarrow = 3 system not speci cally detailed for seismic resistance, there are no additional requirements beyond what is provided in the $\frac{1}{2}$. While the the seismic considerations included in the applicable building code will still apply. ASCE/SEI 7, for instance, includes requirements for horizontal and vertical irregularities, seismic load combinations, collector design and foundation design. Part 3 contains design examples that walk through the design of members and connections for typical > = 3 moment and braced frame lateral systems. This is a valuable resource for engineers designing in both seismic and nonseismic regions, laying out the basis for two of the most commonly implemented connections in lateral force-resisting systems (LFRS).

in the $\gamma_{t} = \rho$, $\rho_{t} = \rho$, that are specific to steel and composite moment frames and braced frames.

Part 4, Moment Frames, addresses system designs for ordinary moment frames, intermediate moment frames and special moment frames (OMF, IMF and SMF, respectively). A number of design examples are then provided for the key members and connections of OMF and SMF systems. Note that in order to avoid repetition, design examples are not provided for IMF systems, considering the extensive overlap of requirements between IMF and SMF systems.

New examples detail two common connection con gurations that meet the stability bracing requirements of an SMF beam. Beam-to-beam connections are designed to provide torsional bracing of the moment-connected beam outside of the protected zone as it extends from the column. The rst of these two examples covers two beams of equal depth (Figure 2) while the second

Part 4 also has an entirely new section on special truss moment frame (STMF) systems. While this system has been included in previous editions of the x_{i} -

 $f = \mathbf{e}_{\mathbf{r}_1,\mathbf{r}_2,\mathbf{r}_3}$, new design examples have been added illustrating the design of this system type. For designers not familiar with this system, an STMF is similar to a moment frame except that it implements a truss as the spanning element between columns instead of a moment-connected beam. Lateral forces and displacements are resisted though the exural and shear strength of the truss chords and web members as well as the columns. Seismic energy is dissipated through inelastic behavior of the special segment at the center few panels of the truss (Figure 4).

Also new to Part 4 is an example related to the $\gamma_{i} - \gamma_{i} = 0$ ($\gamma_{i} + \gamma_{i} + \gamma_{i}$) strong-column, weak-beam requirement, which encourages the ductility of the system to be concentrated in the beams and not the columns. The $\gamma_{i} = 1 + 0 + \gamma_{i} + \eta_{i}$ lists exceptions, and the new example satis es one such exemption, thereby eliminating the need for the designer to meeting this requirement. This particular example in Part 4.

The additional exibility in detailing of web doublers and continuity plates, as found in the latest

Part 5 covers system designs for ordinary and special concentric braced frames (OCBF and SCFB, respectfully). There are also design examples provided for eccentrically braced frames (EBF) and buckling restrained braced frames (BRBF).

The SCBF brace-to-beam connection, or chevron connection, has been expanded to cover the "chevron effect" phenomenon that has been presented in two , -, - in increased bending and shear forces in the supporting beam member within the region of the connection. These increased local forces in the beam may exceed the forces determined from member analysis, and may even exceed the available strength of the beam member. The design example discusses the chevron effect in more detail and provides a method for checking its effect on member design.

Also new in Part 5, Braced Frames, is the connection design of a BRBF brace a beam/column corner gusset plate. This example addresses a case where the brace is provided by a BRB manufacturer